

Master's Research Plan Seminar

# Resource Allocation for Optical IRS-Assisted Multi-UAVs Networks

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Aizuwakamatsu, Dec. 5 2024

# Outline of Presentation

I. Introduction

II. Problem Statement and Motivation

III. Literature Reviews and Its Limitation

IV. Research Goal and Plan Timeline

# 1. The FSO-based HAP networks

In recent years, the success of various projects involving HAPs (e.g., SoftBank's Sunglider in Japan) has opened a new chapter for Aerospace integrated network architecture to support a wide coverage.

## ❖ High-altitude platforms (HAPs)

- Airships, aircraft.
- Altitude: 17-25 km
- Coverage with diameter 200 km
- Provide connection to remote/rural/emergency areas

- Using RF communication: hundreds Mbps and up to a few Gbps



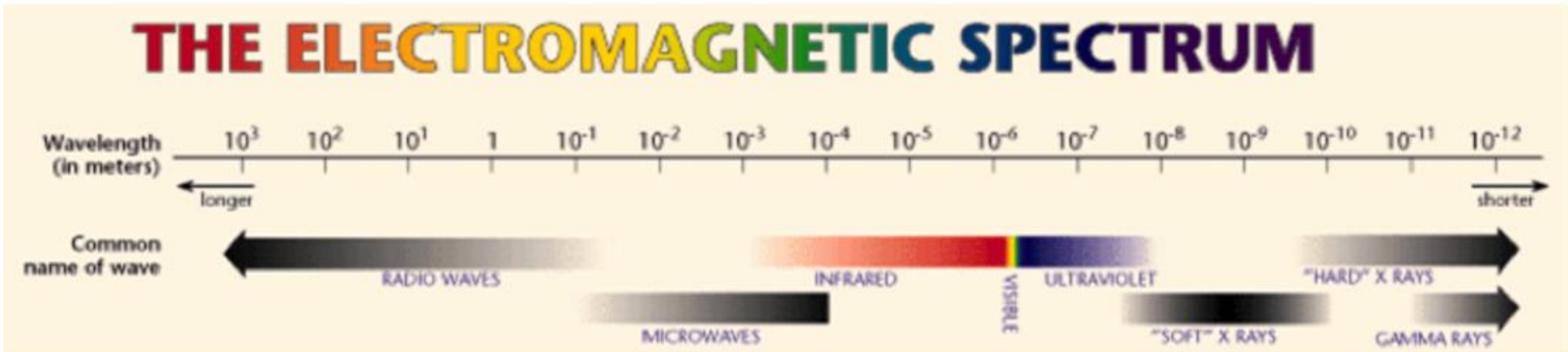
Internet from space by **high altitude platform (HAP)**

➡ Need **higher data rates** to support billions of users for the future 6G network.

# 1. The FSO-based HAP networks

## ❖ Free Space Optical (FSO) communications

- Using infrared frequency bands ( $200\text{-}400\text{ THz}$ ) to transmit data in free space.
- High-speed connection (Gbps and even Tbps)
- Free-license bandwidth



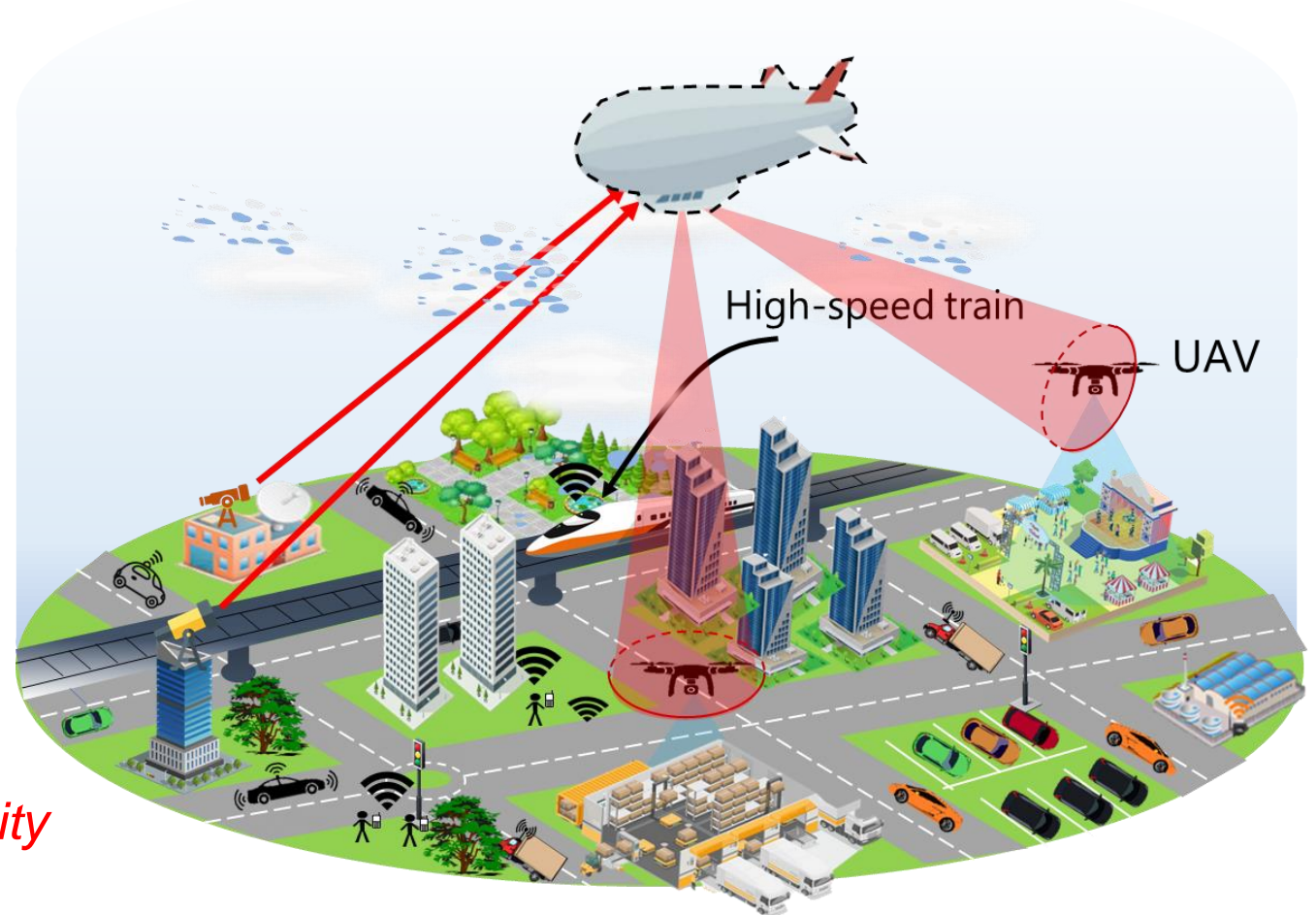
➡ The FSO based HAP can support *ultra-high speed data rate* and *wide coverage*.

# 1. The FSO-based HAP networks

## □ FSO-based HAP network applications:

- Internet of Vehicles (IoV)
- Internet of Medical Things (IoMT)
- Internet of Senses (IoS)
- Internet of Remote Things (IoRT)
- Vehicle to Everything (V2X)
- Smart Grid IoT,...

- However, using HAP as a relay can lead to *power consumption* and *hardware complexity*



The FSO-based HAP-Assisted IoV network

# 1. IRS-assisted FSO-based HAP networks

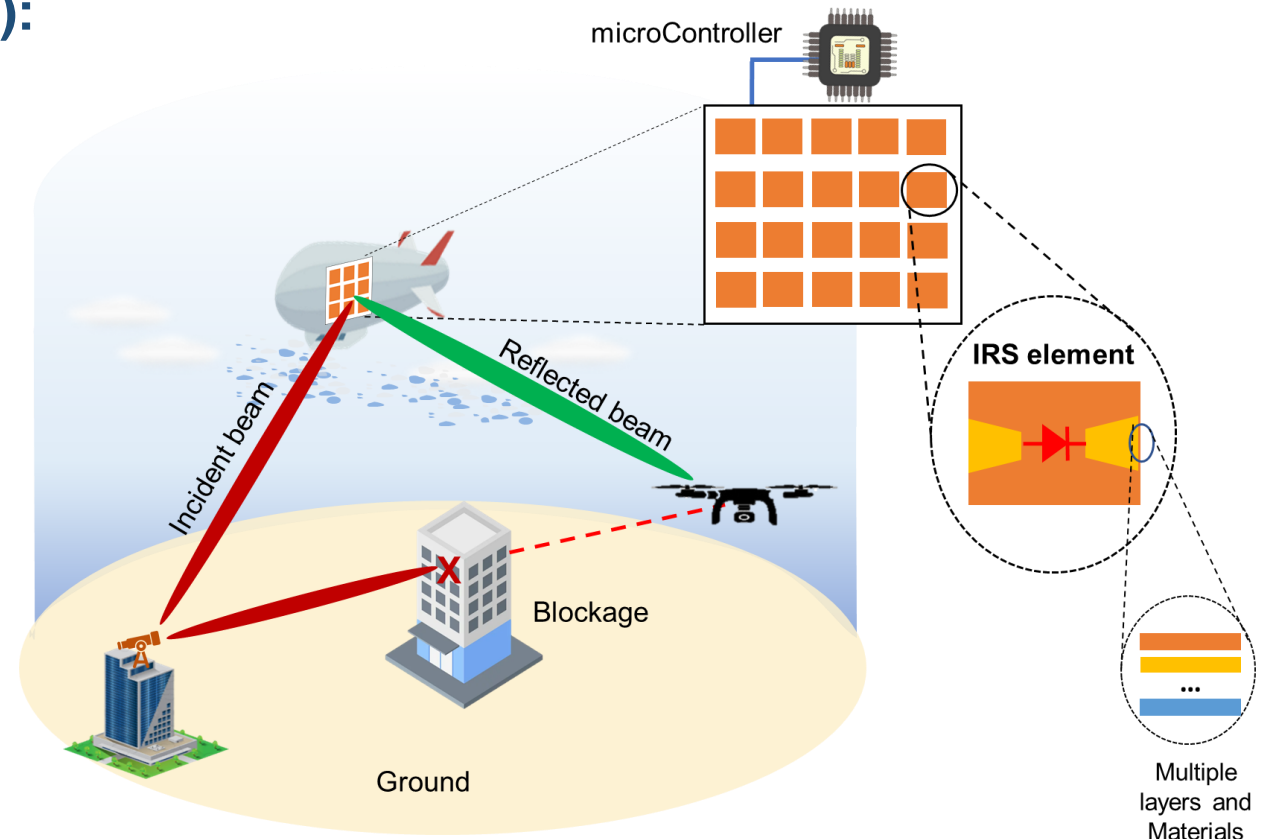
Recently, many works focus on optical intelligent reflecting surface (OIRS) as an alternative solution of conventional relay networks.

## ❖ Optical Intelligent Reflecting Surface (OIRS):

- An artificial surface, made of mirrors and nearly passive elements.
- IRS controls and manipulates the impinging waves into the expected directions.

## ❖ Advantages

- *Low power consumption.*
- *Low complexity and cost-effectiveness*
- *Extend coverage and avoid blockage*

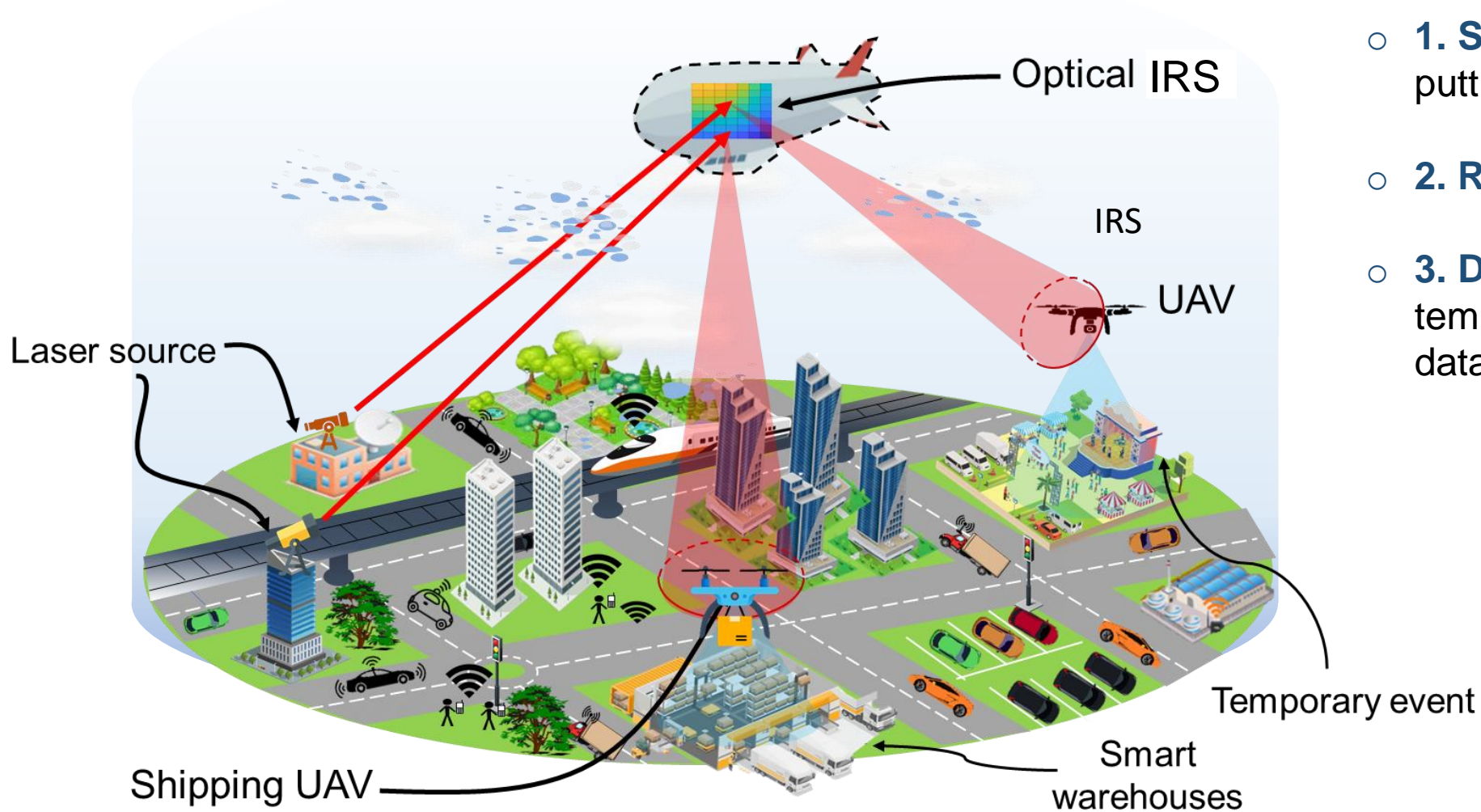


➔ Therefore, IRS can be used for the FSO-based HAP network to support IoV applications.

# 1. Considered Network Scenario

## ❖ System description:

- **1. Sources:** multiple laser sources putting in the top of buildings
- **2. Relay:** one OIRS mounted HAP
- **3. Destinations:** multiple UAVs for temporary event, shipping, rescue, data collection service.

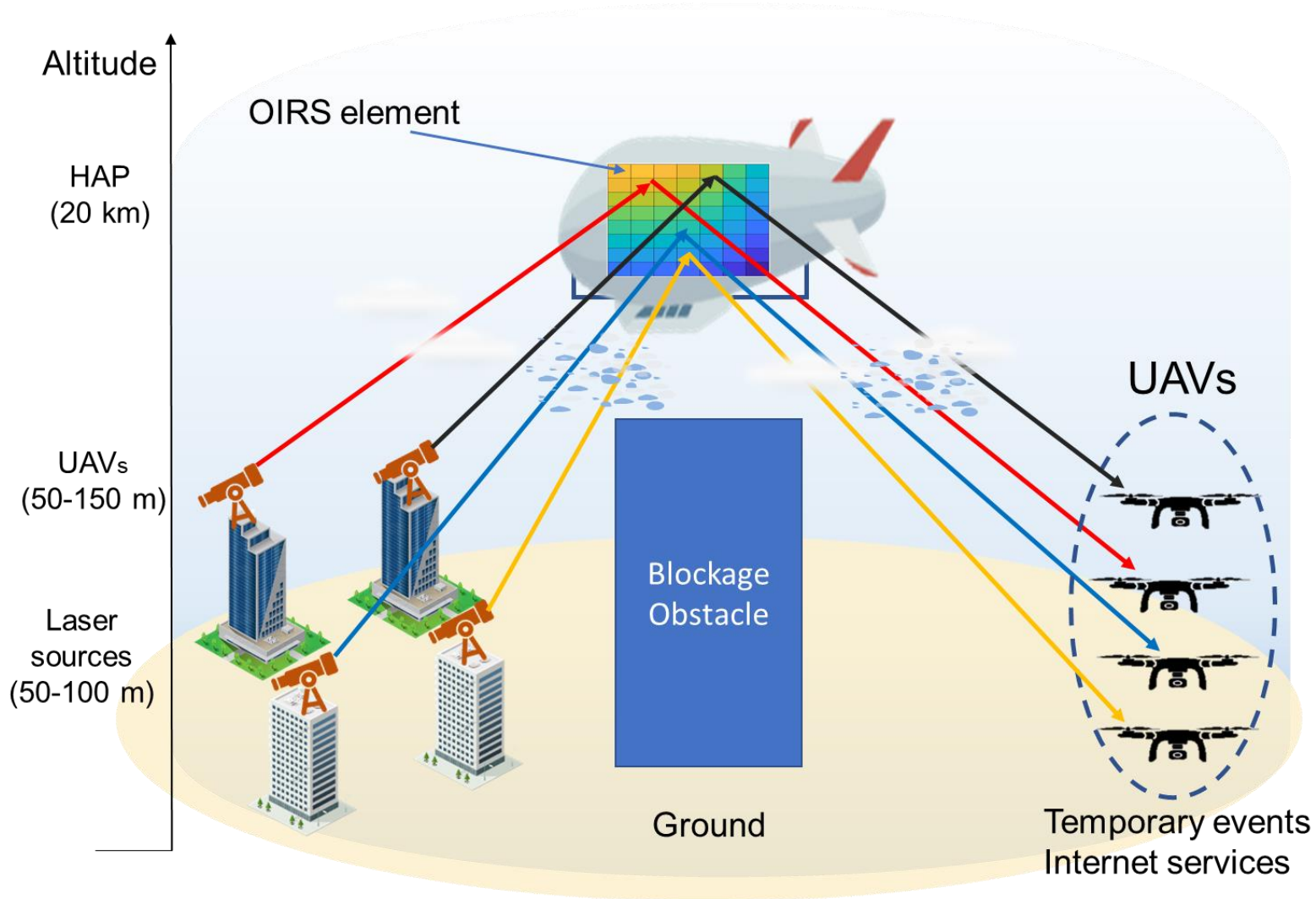


## FSO-based HAP-Assisted Multi-UAVs with IRS

## ❖ Advantages

- Ubiquitous connections
- Wide coverage
- Ultra-high data rate
- Flexible deployment
- Wide range of applications

## 2. Problem Statement



### Limited OIRS Resources

The **limited OIRS size** mounted in HAP restricts the number of OIRS elements, creating critical issues in **sharing these elements** among multiple UAVs.



**Resource Allocation**  
for OIRS supporting  
multiple UAVs

Given:

- Different time-varying channels
- Maintain targeted Quality of Service (QoS) among all UAVs



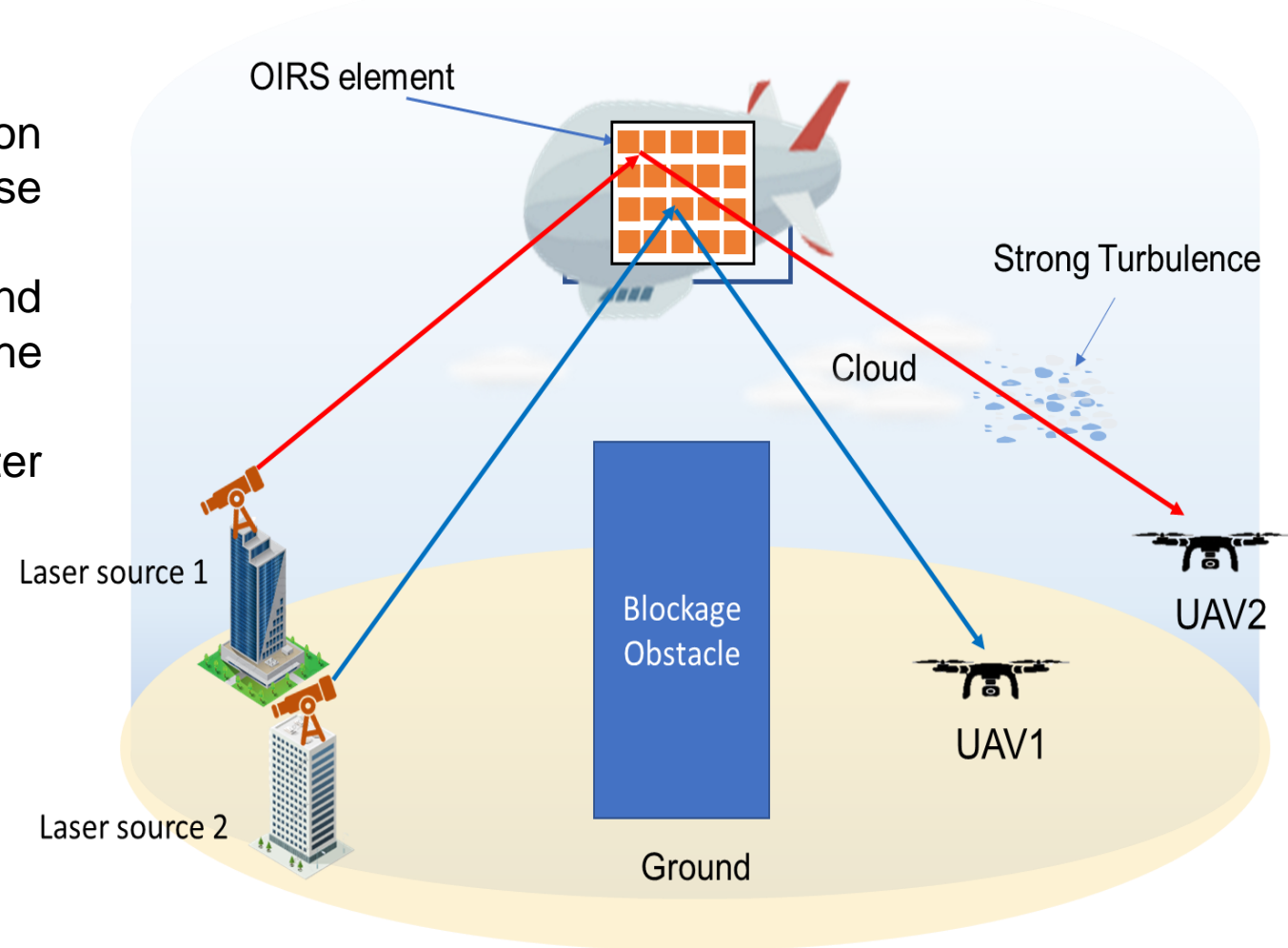
## 2. Problem Statement

### ❖ Time-varying Channel Condition:

- ❑ **Atmospheric turbulence:** random phenomenon temperature and pressure of atmospheric cause the scintillation effect.
- ❑ **Atmospheric attenuation:** the gas molecules and aerosol particles in atmospheric cause the absorbing and scattering phenomenon.
- ❑ **Pointing error:** misalignment between the center of FSO beam footprint and UAV detector.

For example:

- UAV1 is in *good channel condition*, need fewer OIRS elements.
- UAV2 is in *very bad channel condition*, need more OIRS elements.

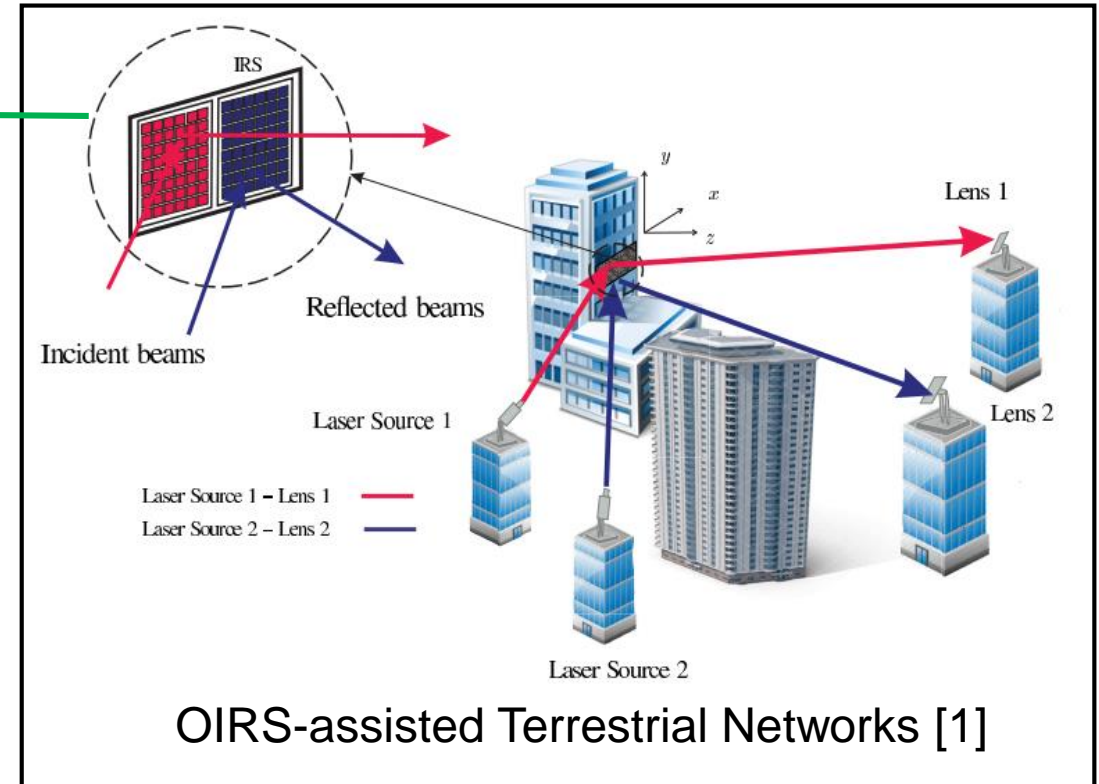
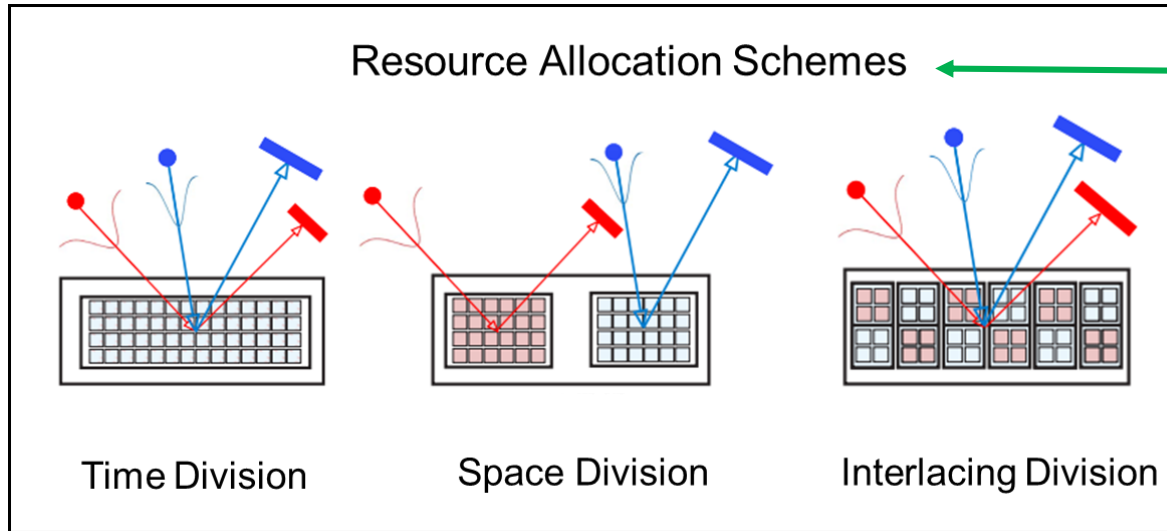


It's important to consider the *dynamic channel conditions* among UAVs to *allocate OIRS elements* for *maintaining a targeted QoS*

### 3. Literature Reviews and Its Limitation

#### □ Terrestrial Networks

Many studies *have well investigated* the OIRS to enhance line-of-sight communication, physical-layer security, and *resource allocation* for both *single user and multiple users* [1]-[3].



➔ However, these schemes *allocate OIRS equally* to multiple users and is *not straight-forward* to apply in space with *dynamic channel conditions*.

### 3. Literature Reviews and Its Limitation

#### ❑ Space Networks

In space networks, many studies have focused on using IRS to avoid bad weather conditions or blockage connections in the context of a **single user** [4]-[6].

Reference	Summary
[4]-2022	Analyze the performance of a reconfigurable intelligent surface (RIS)-assisted unmanned aerial vehicle (UAV) wireless system that is affected by mixture-gamma small-scale fading, stochastic disorientation and misalignment, as well as transceivers hardware imperfections. <i>=&gt; Do not consider resource allocation</i>
[5]-2023	This paper examines hybrid FSO-RF relay systems in satellite-terrestrial networks, considering weather effects and propose design three relay schemes for varying weather using HAPS and RIS-assisted UAVs. <i>=&gt; Can't support in term of multiple users simultaneously</i>
[6]-2024	Introduce multi-hop fully FSO-backhaul link, connecting ground stations through RIS-embedded UAVs. <i>=&gt; Do not consider the multiple users and time-varying channel</i>

 Resource allocation for ORIS supporting **multiple users** considering different **time-varying channel conditions and QoS** of all UAVs is not available.

### ❖ Research Goal

- I want to propose a resource allocation mechanism based on Space and Interlacing Division considering (1) **the different channel conditions**, (2) **fixed OIRS elements**, and the (3) **Quality of Services (QoS)** (e.g Outage Probability/Bit error rate) among UAVs.

➡ Calculate the required number of OIRS elements  $(n_i)$  for each UAVs.

➡ Determine the coordinates of each OIRS element  $(x_i, y_i)$  in OIRS panel.

$$\text{Throughput}_i, \tau_i = f(n_i, x_j, y_k)$$

$$\max_{(n_i, x_j, y_k)} (\text{Total\_Throughput}) = \sum_{i=1}^N \tau(i),$$

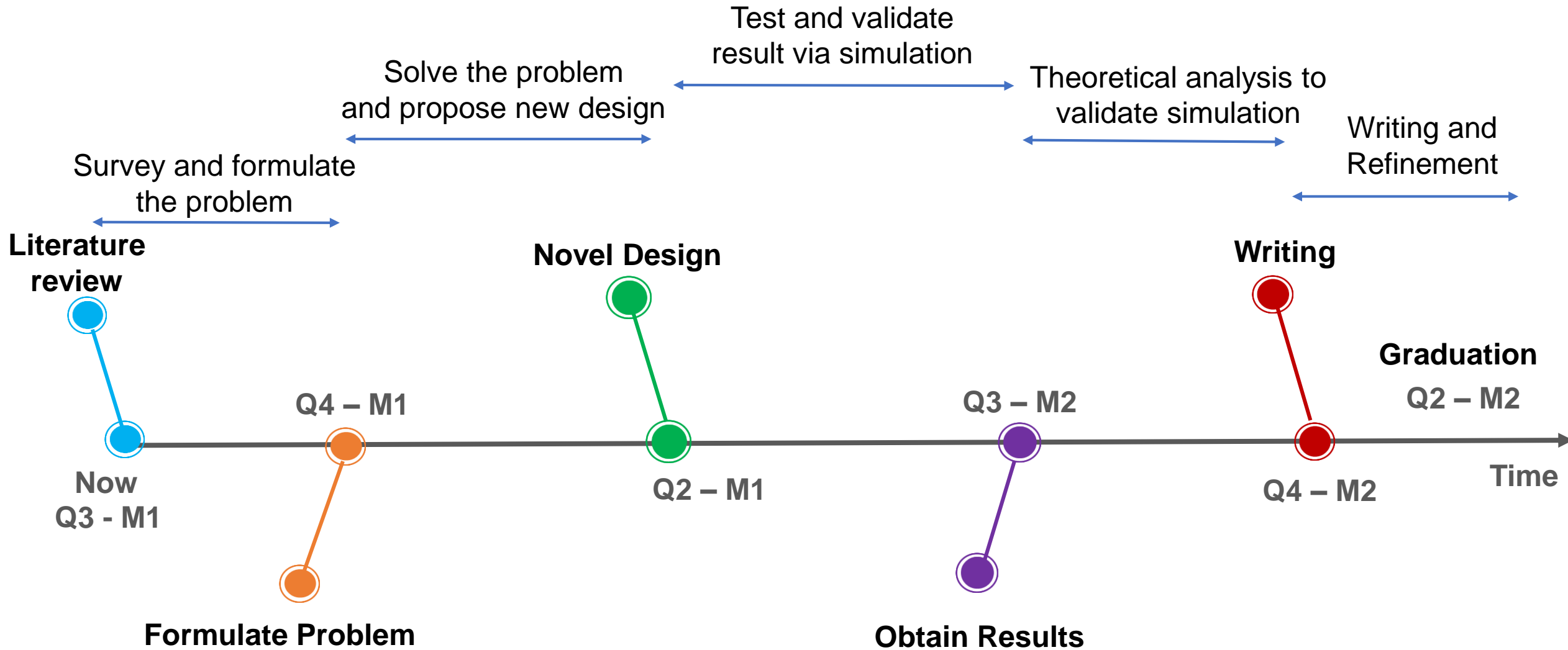
$$\text{s.t } QoS_{\text{targeted}}, \text{fixed OIRS size} = M_X \times M_Y$$

where  $i \in \{1, 2, \dots, N\}$ , where  $N$  is number of UAVs,

$j \in \{1, 2, \dots, M_X\}$ , where  $M_X$  is number of OIRS in X coordinate,

$k \in \{1, 2, \dots, M_Y\}$ , where  $M_Y$  is number of OIRS in Y coordinate.

# 4. Research Goal and Plan Timeline



**THANK YOU FOR LISTENING!**

# Reference

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