Autoencoders for Probabilistic Constellation Shaping

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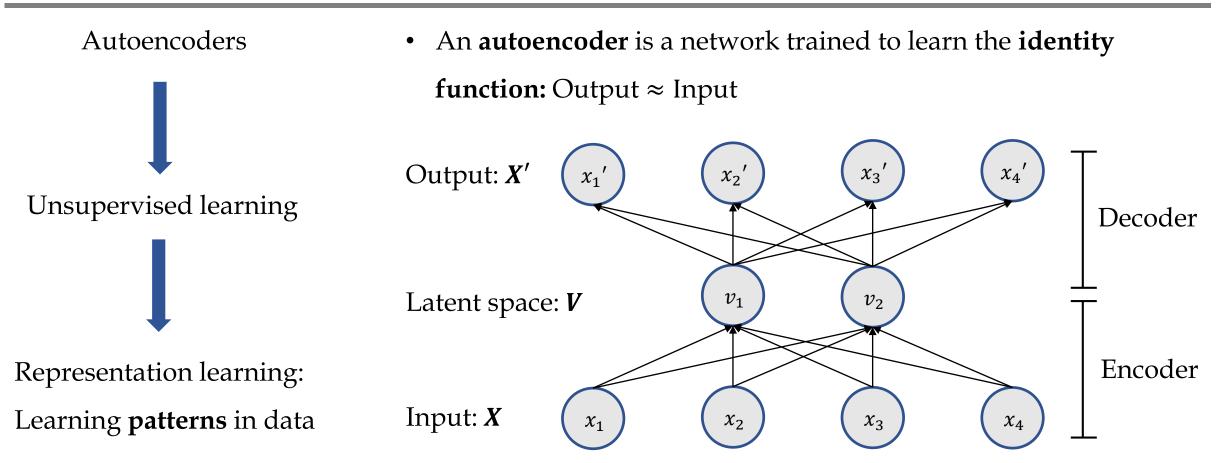
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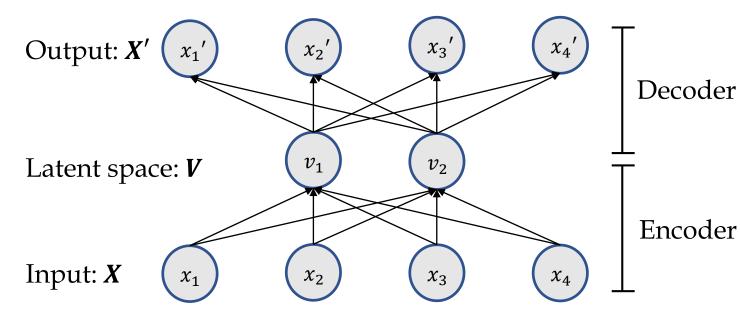
Basic idea



- Encoder *f*(**X**) maps input to a lower-dimensional representation (latent space **V**)
- **Decoder** g(V) decompress representation back to original domain (X')

Basic idea

- Basic idea: Create an architecture with a latent space (bottleneck layer), which ensures a lower-dimensional representation of the original data
- □ The latent space keeps the most important attributes of the input data



Why autoencoders?

- Map high-dimensional data to low dimensions for visualization
 - Compression
 - Learn abstract features of data

But how do we train an autoencoder?

Training

Minimize reconstruction error:

Original data Reconstructed data

E(|X|, |X'|)

Backpropagation algorithm

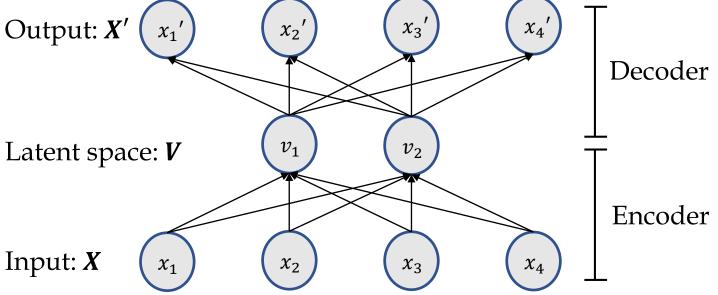
□ Requirement for an autoencoder:

Input: X

1. Sensitive enough to input data to reconstruct it

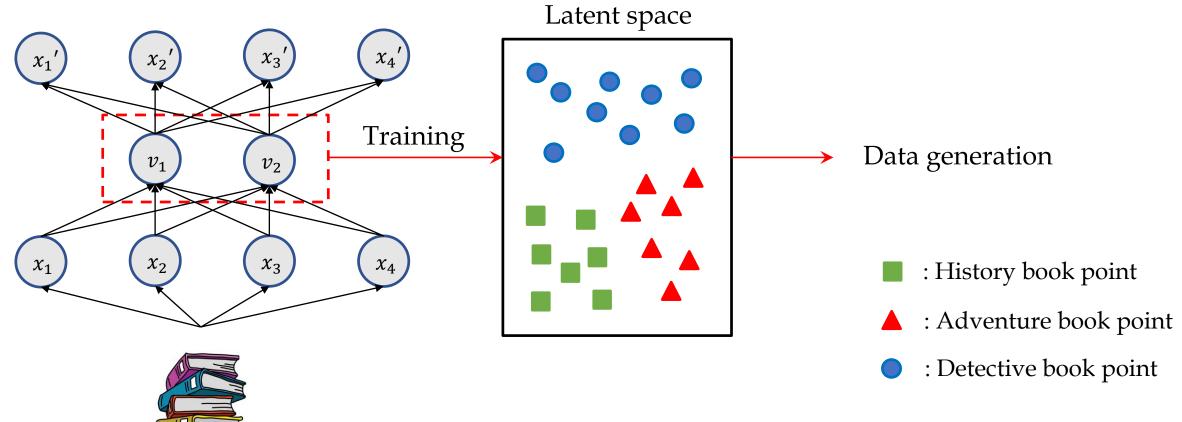
2. Insensitive enough to input data **not** to overfit it

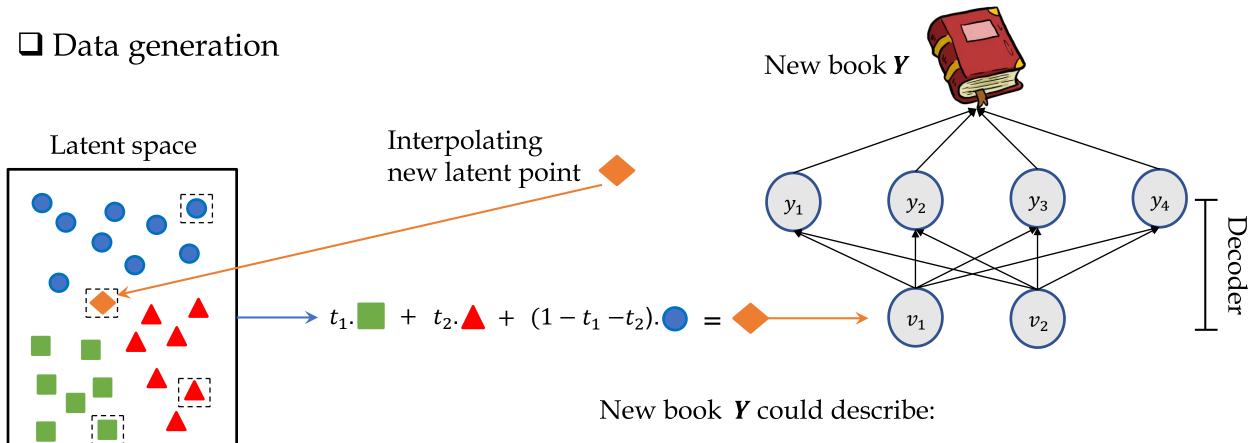




□ The latent space keeps the most important attributes of the input data

We can leverage the latent space to perform several interesting tasks





- : History book point
- Adventure book point
- Detective book point

• A detective adventure that takes place

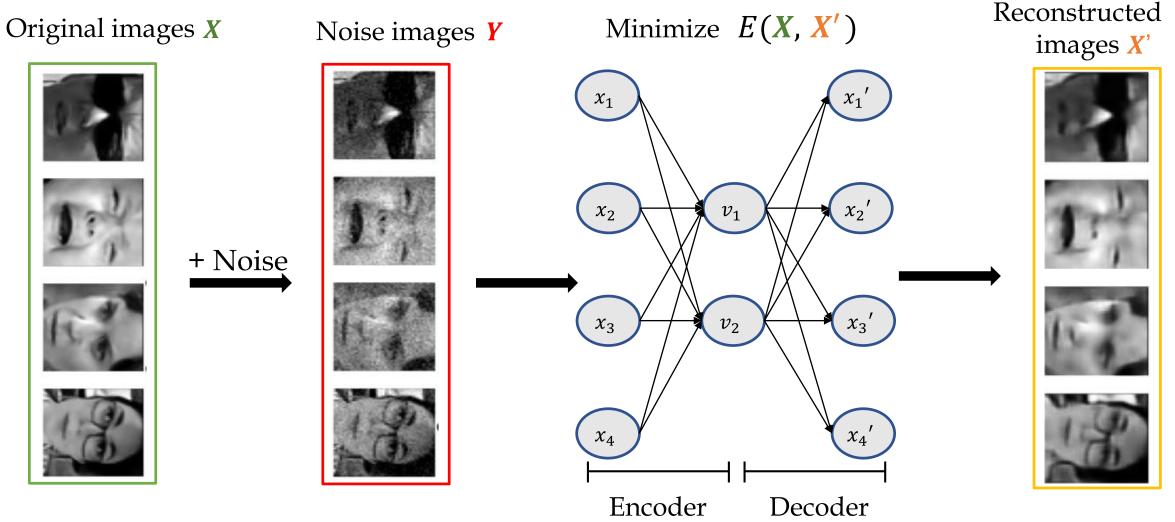
during a historical event

• Discuss the historical event with a

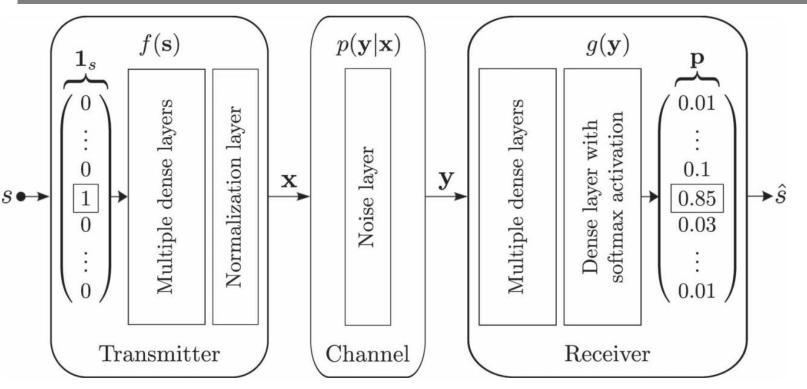
detective adventurous narrative style

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Denoising



This concept can be applied to **an end-to-end communication system**



A communication system over an AWGN channel represented as an autoencoder [1]

- Input **s**: The transmitted symbol $s \in \{1, ..., M\}$
- Output *p*: Probability vector over all possible symbol
- *ŝ*: Estimated the transmitted symbol

[1] T. O'Shea and J. Hoydis, "An Introduction to Deep Learning for the Physical Layer," in *IEEE Transactions on Cognitive Communications and Networking*, vol. 3, no. 4, pp. 563-575, Dec. 2017, doi: 10.1109/TCCN.2017.2758370.

- The autoencoder is trained on the set of all possible transmitted symbol *s*
- Loss function is the categorical cross entropy between 1_s and p
- It learns an intermediate
 representation x of s
 (constellation, coding) robust
 to channel perturbations

- □ Visible light communication (VLC)
- □ Probabilistic constellation shaping (PCS)
- □ Autoencoder-based PCS design
- □ Extension and direction

Visible light communication

□ It uses the emitted light from the light-emitted diode (LED) as a transmission medium

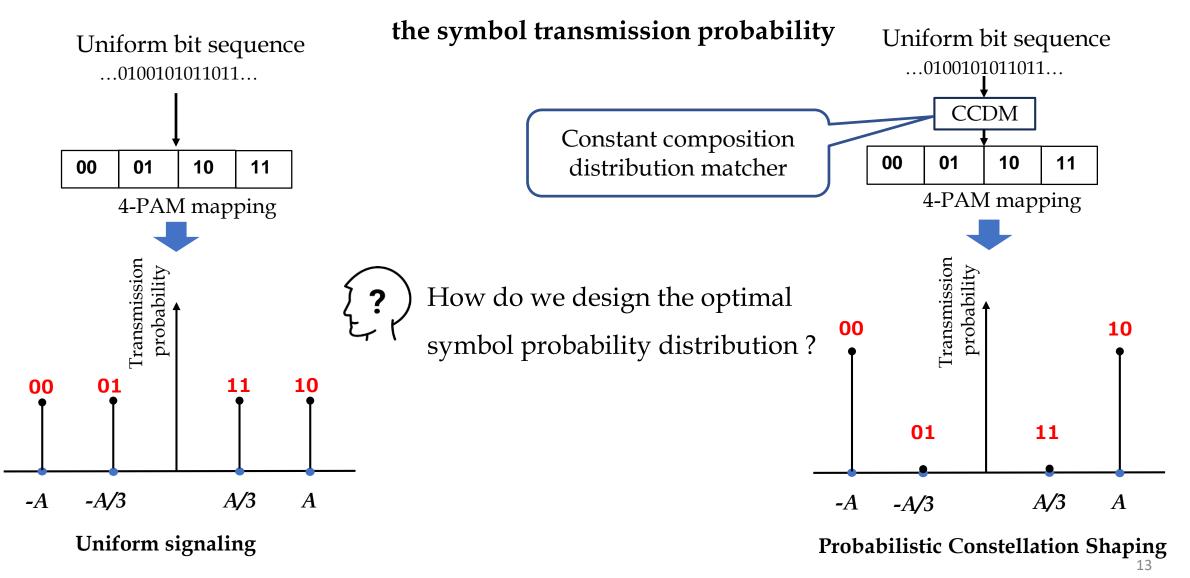


- Dual functionality
 - Illumination (primary)
 - Communication (secondary)
- Immunity to interference from other electromagnetic sources
- Environment friendly
 - Hospital
 - Airplane

However, the practical deployment of VLC systems faces challenges in **achieving high transmission rates** under peak amplitude constraints of the LEDs

Probabilistic constellation shaping

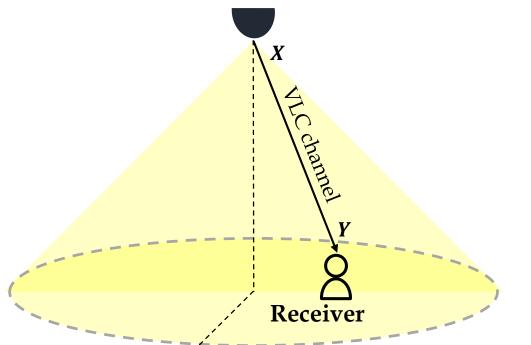
□ Probabilistic constellation shaping is an approach to improve the achievable rate by **designing**



Probabilistic constellation shaping

) How to design the optimal symbol probability distribution?

LED transmitter

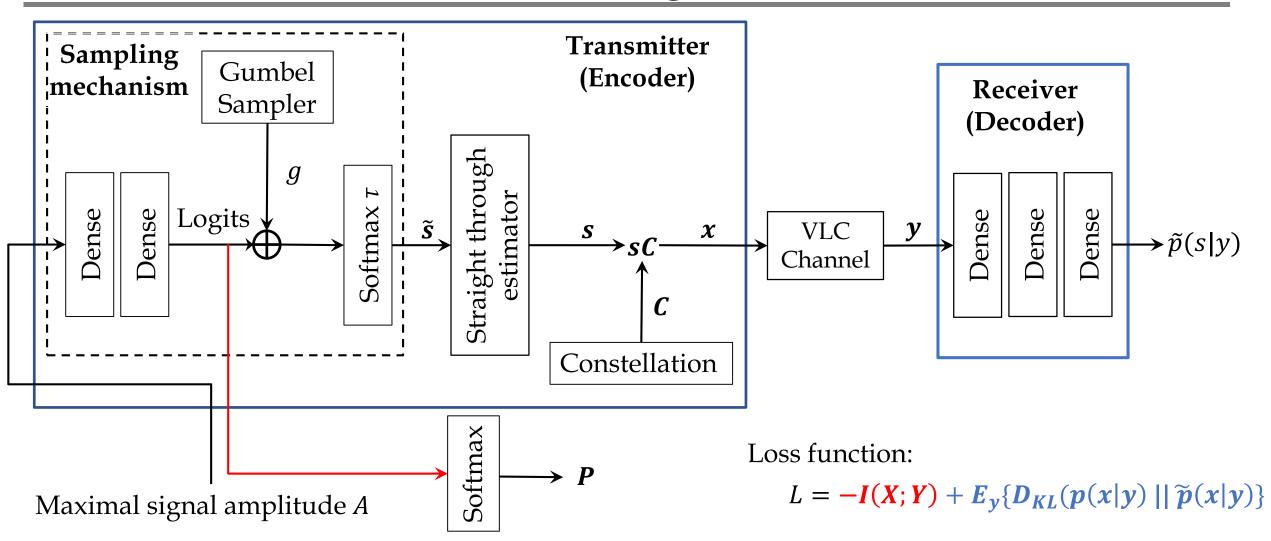


Single input single output (SISO) visible light (VLC) communication system

- **Purpose**: Maximize the achievable rate between the LED transmitter and receiver
- **Variable**: Symbol probability distribution *P* of M-PAM constellation
- Achievable rate I(X, Y):
 - Amount of information that one random variable Y contains about another random variable X
 - Measure the reduction in uncertainty about X given the knowledge of Y

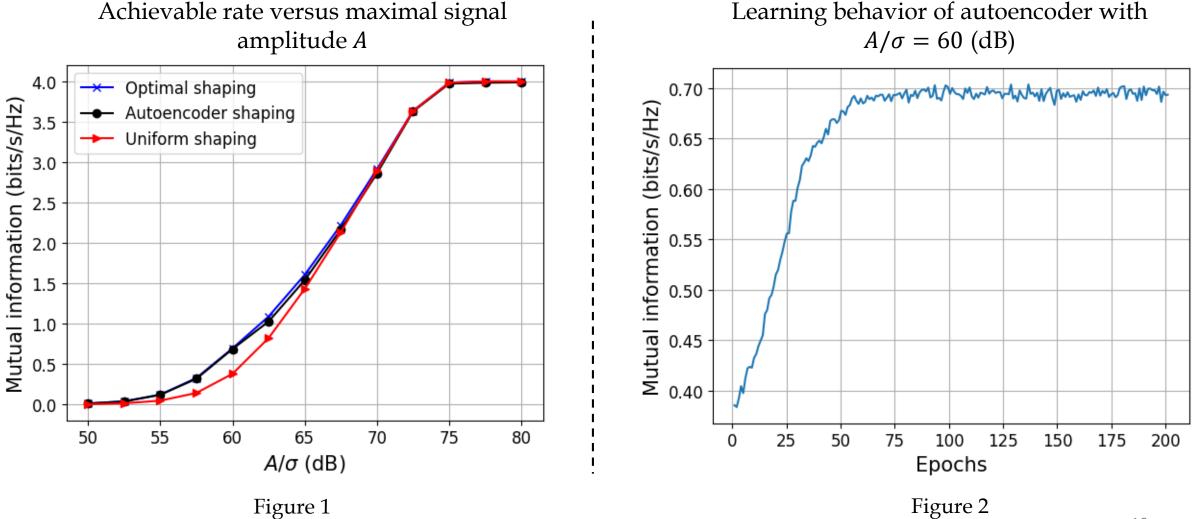
Representing the **end-to-end SISO VLC system** as **an autoencoder** is an approach to learning the optimal symbol distribution

Autoencoder-based PCS design



The autoencoder learns a sampling mechanism (*P*) of transmitted symbols to maximize the achievable rate and minimize the error construction of transmitted symbol *s* at the receiver

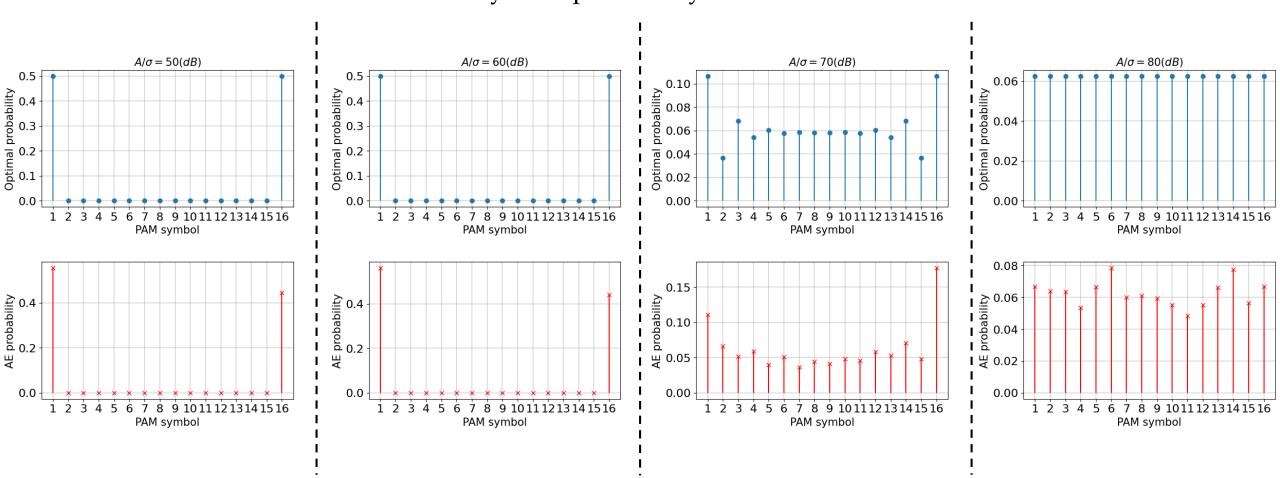
Current results



Autoencoder-based PCS design

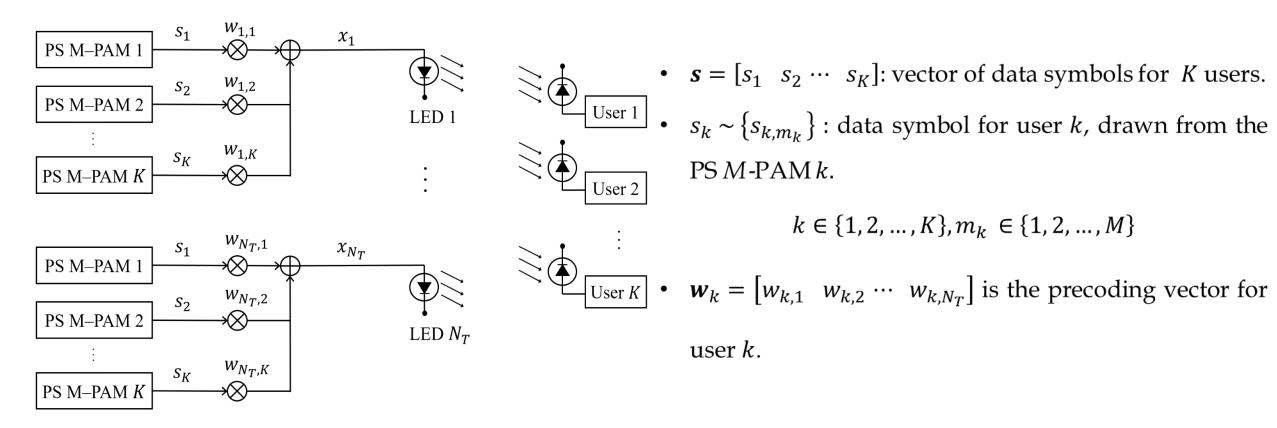
□ Current results

Symbol probability distribution



Extension and direction

□ Extend the PCS design for multiple transmitters and multiple users scenario

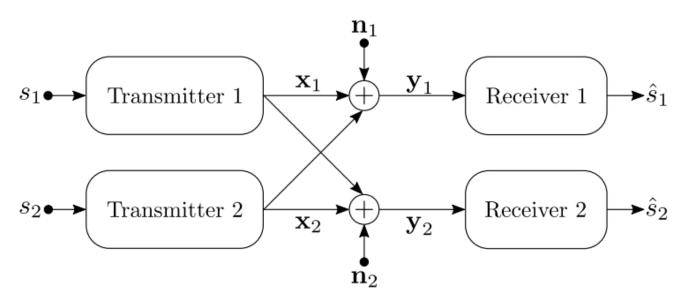


- ➢ Besides symbol distribution P, the precoding matrix W is another optimization variable
- The autoencoder network needs to be modified

Extension and direction

Extend the PCS design for multiple transmitters and multiple users scenario

• Both transmitter-receiver pairs are implemented as autoencoders



- The two-user interference channel is seen as a combination of **two interfering autoencoders** that try to maximize the sum of achievable rates and reconstruct their respective symbols
- The two autoencoders will be trained to learn both the sampling mechanism (*P*) and the internal representation of transmitted symbol with the precoding matrix (*W*)

Extension and direction

□Extend the PCS design for multiple transmitters and multiple user scenarios with channel uncertainty

- Current work: PCS and precoding design with the **perfect knowledge** about the channel state information (CSI) in the transmitter
- Practical scenario: Due to users movements, CSI is **imperfect** due to outdated feedback or erroneous channel estimation

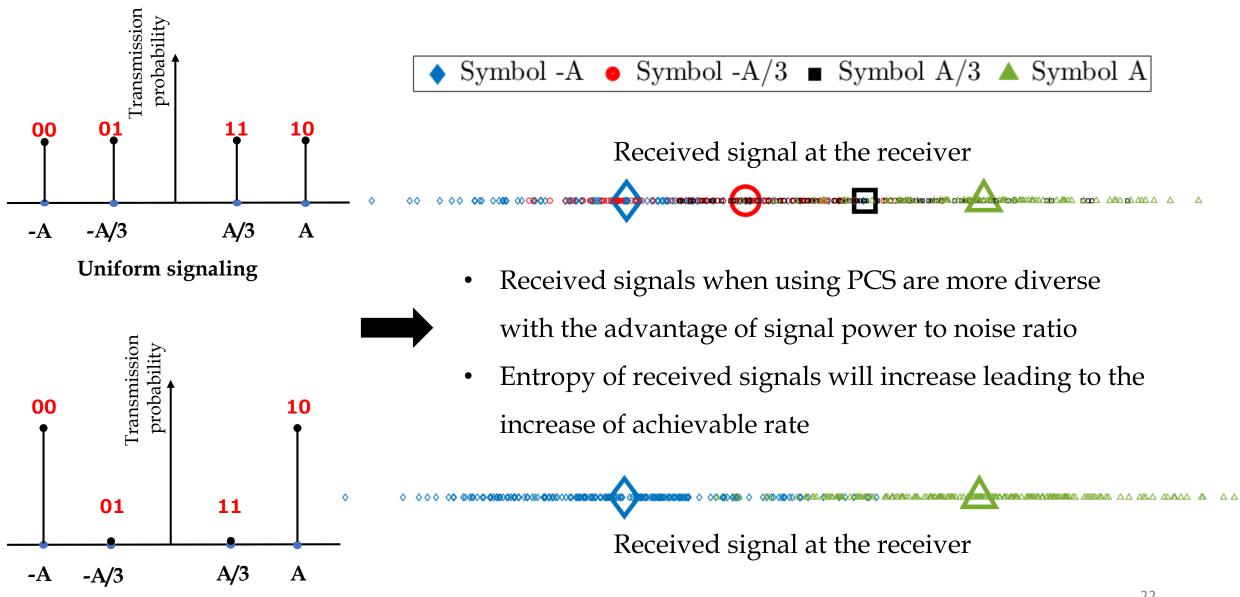


Robust designs needed to be addressed

- Worst-case problem: guarantee **a certain performance** level for all possible channel realizations
- Average problem: guarantees **an average performance** over possible error realizations

Thank you for listening! Q&A

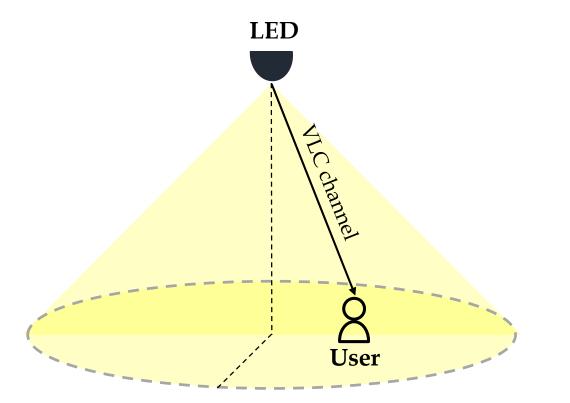
Probabilistic constellation shaping



Probabilistic Constellation Shaping

Probabilistic constellation shaping

Let s₁, s₂, . . ., s_M be M bipolar M-PAM symbols generated from CCDM and constellation mapping
 a_m(0 < a_m < A), p_m are the amplitude and transmission probability of s_m



Single input single output (SISO) visible light (VLC) communication system

• Received electrical signal at user: $y_{\rm U} = h_{\rm U} \gamma \eta (s + I_{\rm DC}) + n_{\rm U}$

 $h_{\rm U}$: line-of-sight (LoS) channel gain γ : photodetector's responsivity η : LED's electrical-to-optical conversion factor $I_{\rm DC}$: DC bias $n_{\rm U} \sim \mathcal{N}(0, \sigma_{\rm U}^2)$: Gaussian reicever nosie

Removing the DC bias which carries no information

$$\overline{y}_{\mathrm{U}} = h_{\mathrm{U}} \gamma \eta s + n_{\mathrm{U}}$$